

## DEXTEROUS HANDS SERIES









	Hand Plus	Hand Lite	Hand Extra Lite	Hand Super Lite
Fingers + Thumb	4+1	3+1	2+1	1+1
Joints	24	16	12	8
Degrees of Freedom	20	13	10	7
Tactile Sensors (Pressure Sensor Tactiles)	/	<b>✓</b>	/	/
Height	448mm	327mm	327mm	327mm
Weight	9.47lb	5.29lb	3.96lb	2.64lb
Payload	up to 8.81lb	up to 8.81lb	up to 6.61lb	up to 4.4lb
ROS Open-Source Platform	~	~	·	<b>~</b>
Easily Integrated on Robot Arms	/	~	/	<b>✓</b>
Upgradable	/	/	/	✓ ·