

# Contention Resolution in Multiple-access Channels: $k$ -Selection in Radio Networks

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# Shared Resource Contention

- Unique resource to be shared among many users
- All contenders must have access eventually
- Only one user at a time may have access

⇒ Contention.

- Unknown number of contenders

⇒ up to  $n$ .

- E.g.:  $k$ -Selection in Radio Networks:

“unknown size- $k$  subset of network nodes  
must access a unique shared channel of communication,  
each of them at least once.”

- Q:  $k$ -Selection with unknown  $k$  in  $O(k)$ ?

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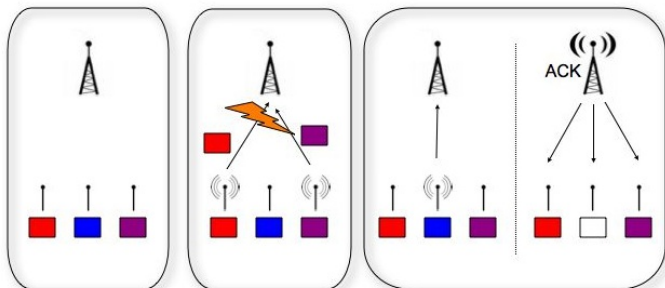
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# Radio Network Model and Notation

- labeled stations called *nodes*.
- no information except own ID (unique, arbitrary) and  $n$ .
- time slotted in communication steps.
- nodes are potentially reachable in one comm step  $\rightarrow$  *single-hop*.
- time complexity = communication steps (negligible computation cost).
- piece of information to deliver called *message*.
- node is *active* if holds a message to deliver.
- message assignment is external (called message *arrival*).
- *batched* message arrivals (*static k-Selection*).
- number of messages left to deliver called *density*.

# Radio Network Model

- communication through radio broadcast on a shared channel.
- in one step:
  - no message transmitted  $\rightarrow$  all nodes receive background noise.
  - more than one node transmits  $\rightarrow$  all other nodes receive interference noise. (collision, messages garbled, etc.)
  - exactly one node transmits  $\rightarrow$  all other nodes receive message and the sender receives an ack.  
(successful transmission, message delivered, single transmission, etc.)
- nodes can not distinguish between interference and background noise.



# Related Work

## Randomized

- With collision detection:
  - Willard'86:
    - Expected  $\log \log k + o(\log \log k)$  for *Selection* with unknown  $n$ .
  - Martel'94:
    - $k$ -Selection expected  $O(k + \log n)$  with known  $n$ .  
Kowalski'05: can be improved to expected  $O(k + \log \log n)$  using Willard's.
- Without collision detection:
  - Kushilevitz, Mansour'98:
    - For any given protocol,  $\exists k$  s.t.  
expected  $\Omega(\log n)$  to get even the first message delivered.



# Related Work

## Beyond Radio Networks

- Greenberg, Leiserson'89: *randomized routing of bounded number of messages in fat-trees*  $\Rightarrow$   $k$ -Selection if constant edge-capacities.  $\Rightarrow$  logarithmic congestion parameter  $\Rightarrow O(k \text{ polylog } n)$ .
- Geréb-Graus, Tsantilas'92: *arbitrary  $h$ -relations realization* in  $\Theta(h + \log n \log \log n)$  w.h.p.  $\Rightarrow$   $k$ -Selection if  $h = k$ . Needs  $h$  known.
- Bender, Farach-Colton, Kuszmaul, Leiserson'05: *Back-off strategies for contention resolution of batched arrivals of  $k$  packets on simple multiple access channels*  
 $\log \log$ -iterated back-off  $\rightarrow \Theta(k \log \log k / \log \log \log k)$   
w.p.  $\geq 1 - 1/k^{\Theta(1)}$ , without knowledge of a bound on  $k$ .

# Related Work

## Deterministic

- *Tree* algorithms:  $O(k \log(n/k))$  [H'78, MT'78, C'79]. Adaptive, with collision detection.
- Greenberg, Winograd'85: tree algorithms take  $\Omega(k \log_k n)$ .
- Greenberg, Komlòs'85:  $\exists$  *oblivious* protocols  $O(k \log(n/k))$  even without collision detection if  $k$  and  $n$  are known.
- Clementi, Monti, Silvestri'01: matching lower bound. Also holds for *adaptive* protocols if no collision detection.
- Kowalski'05: oblivious deterministic protocol  $O(k \text{ polylog } n)$  without collision detection, using Indyk'02 explicit selectors.

# Result

- Back-on/back-off Randomized  $k$ -Selection in one-hop Radio Network in  $(e + 1 + \xi)k + O(\log^2(1/\varepsilon))$  with probability  $\geq 1 - \varepsilon$  unknown  $k$  ( $\xi > 0$  arb. small constant).
  - Optimal (modulo a small constant factor  $< 4$ ) if  $\varepsilon \in \Omega(2^{-\sqrt{k}})$ .
  - Given  $\Omega(k \log \log k / \log \log \log k)$  [Bender et al.'05] for monotonic back-off, shows separation using back-on strategies.
  - Improves over loglog-iterated back-off  $O(k \log \log k / \log \log \log k)$  [Bender et al.'05] by exploiting back-on and knowledge of  $n$ .
  - Error probability is parametric  $\Rightarrow$  suitable to be used in multi-hop Radio Networks.

# Protocol for node $x$

without constants

- Algorithm AT: (if  $\delta > \log(1/\varepsilon)$  messages left)

Concurrent Task 1:

$t = \log(1/\varepsilon)$ . (set up a step counter)

$\hat{\delta} = \log(1/\varepsilon)$ . (set up a density estimate)

for each communication step

transmit  $\langle x, message \rangle$  with probability  $1/\hat{\delta}$ .

$t = t - 1$ .

if  $t \leq 0$

$t = \log(1/\varepsilon)$ . (new round)

$\hat{\delta} = \hat{\delta} + \log(1/\varepsilon)$ . (update estimate)

Concurrent Task 2:

upon receiving a message from other node

$\hat{\delta} = \max\{\hat{\delta} - 1, \log(1/\varepsilon)\}$ . (update estimate)

$t = t + 1$ . (stretch round)

Concurrent Task 3:

upon delivering message, stop.

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- Algorithm BT: (if  $\delta \leq \log(1/\varepsilon)$  messages left)  
for each communication step  
transmit  $\langle x, message \rangle$  with probability  $1/\log(1/\varepsilon)$ .

# Protocol for node $x$

without constants

But we do not know  $\delta \rightarrow$  interleave both:

Concurrent Task 1:

$$t = \log(1/\varepsilon), \hat{\delta} = \log(1/\varepsilon).$$

for each communication step

if step is even (Algorithm BT)

transmit  $\langle x, message \rangle$  with probability  $1/\log(1/\varepsilon)$ .

if step is odd (Algorithm AT)

transmit  $\langle x, message \rangle$  with probability  $1/\hat{\delta}$ .

$$t = t - 1.$$

if  $t \leq 0$

$$t = \log(1/\varepsilon), \hat{\delta} = \hat{\delta} + \log(1/\varepsilon).$$

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# Analysis

## Time Efficiency

- Failure steps:
  - Algorithm AT:
    - At most  $k/\log(1/\varepsilon)$  rounds until the estimate reaches  $k$ .
    - Each round includes  $\log(1/\varepsilon)$  failure steps.
  - Algorithm BT:
    - After  $\leq \log(1/\varepsilon)$  messages are left, in  $O(\log^2(1/\varepsilon))$  steps w.p.  $1 - \varepsilon$  BT delivers all.
- Success steps:
  - One step per message delivered  $\Rightarrow k$  overall.
- Overall:
  - $(e + 1 + \xi)k + O(\log^2(1/\varepsilon))$   
(there are some constants...)

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## Correctness sketch

### Lemma

*Until the estimate  $\hat{\delta}$  is some “constant close” to the number of messages left  $\delta$ , within a round, the probability of passing a message is not positively correlated with time.*

### Lemma

*If  $\hat{\delta}$  is “logarithmically close” to  $\delta$  at the beginning of a round, until the number of messages delivered in this round is logarithmic, the probability of delivering a message is at least constant.*

$\implies$  we can bound from below logarithmically the number of messages delivered in each round where the estimate is “close” to the number of messages left using Chernoff.

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## Correctness sketch

### Lemma

*If  $\delta$  is more than some logarithmic number  $M$ , after running the AT-algorithm for  $(e + 1 + \xi)k$  steps, where  $\xi > 0$  is any constant arbitrarily close to 0,  $\delta \leq M$  with probability at least  $1 - \varepsilon$ .*

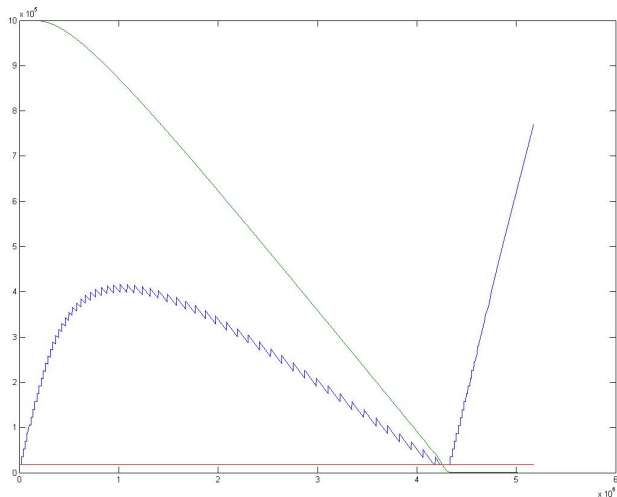
### Proof.

- Using Chernoff, the probability of reducing  $\delta$  logarithmically in each round after  $\hat{\delta}$  is "logarithmically close" is at least  $1 - \varepsilon/(k + \varepsilon)$ .
- Using an inductive argument over rounds and conditional probabilities,  $\delta \leq M$  in one pass with probability at least  $1 - \varepsilon$ .



# Analysis

## Illustration of estimate progress





# Analysis

## Correctness sketch

Together with Algorithm BT...

### Theorem

*For any one-hop Radio Network, under the model detailed, the protocol described solves the  $k$ -selection problem within  $(e + 1 + \xi)k + O(\log^2(1/\varepsilon))$  communication steps, where  $\xi > 0$  is any constant arbitrarily close to 0, with probability at least  $1 - \varepsilon$ .*

# Application

Farach-Colton, Fernández Anta, Mosteiro

*Optimal Memory-Aware Sensor Network Gossiping*

Phases of the algorithm:

- 1 Partition nodes in *masters* and *slaves*  
 $\Rightarrow \text{MIS} \rightarrow O(\log^2 n)$
- 2 Every master reserves blocks of time steps for local use  
 $\Rightarrow \text{Coloring} \rightarrow O(\log n)$
- 3 Every master maintains set of messages received  
 $\Rightarrow \text{back-on/back-off} \rightarrow O(\Delta + \log^2 n)$
- 4 Every master disseminates local set  
 $\Rightarrow \text{flooding among masters} \rightarrow O(D)$

Overall:

$$O(\log^2 n + \log n + \Delta + \log^2 n \log \Delta + D) \in O(\Delta + D) \text{ w.h.p.}$$

# Future Work

- ➊ Remove the knowledge of  $n$ .
- ➋ Generalize the system model:
  - Continuous message arrival.
  - Arbitrary wake-up.
- ➌ Evaluation of the algorithm:
  - Study its practicality by simulation.
  - Compare it with other algorithms (e.g., Bender et al).
  - Improve its constants.

Thank you