

# Polynomial Counting in Anonymous Dynamic Networks

with Applications to  
Anonymous Dynamic Algebraic Computations

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# The Internet of Things



Vehicle, asset, person & pet  
monitoring & controlling



Agriculture automation



Energy consumption



Security &  
surveillance



Building management



Embedded  
Mobile

Internet of things

Everyday things  
get connected for smarter  
tomorrow



M2M & wireless  
sensor network



Everyday things



Smart homes & cities



Telemedicine & healthcare

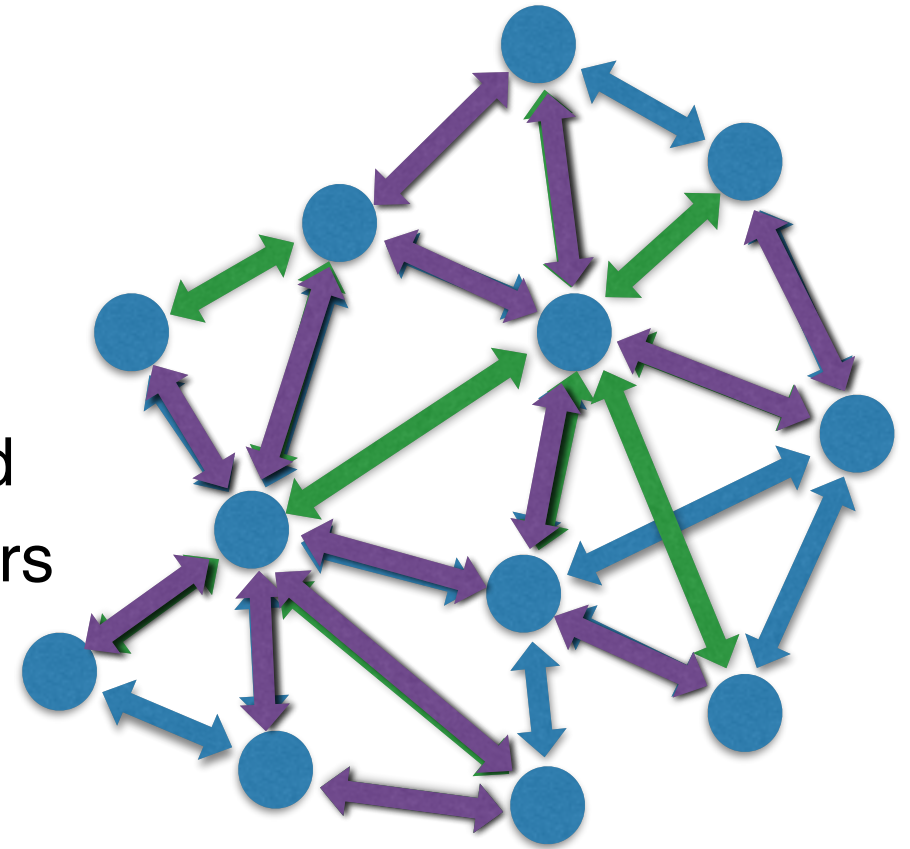


Source: Mario Morales, IDC



# Anonymous Dynamic Networks

- **Fixed set of  $n$  nodes**
  - No identifiers or labels
  - A special node, called the leader [1]
- **Synchronous communication** : At each round
  - a node broadcasts a message to its neighbors
  - receives the messages of its neighbors
  - executes some local computation
- **1-interval connectivity** [2]
  - communication links may change from round to round, but
  - at each round the network is connected



[1] O. Michail, I. Chatzigiannakis, and P. G. Spirakis. Naming and counting in anonymous unknown dynamic networks. SSS 2013.

[2] F. Kuhn, N. A. Lynch, R. Oshman. Distributed computation in dynamic networks. STOC 2010.

# The Counting Problem

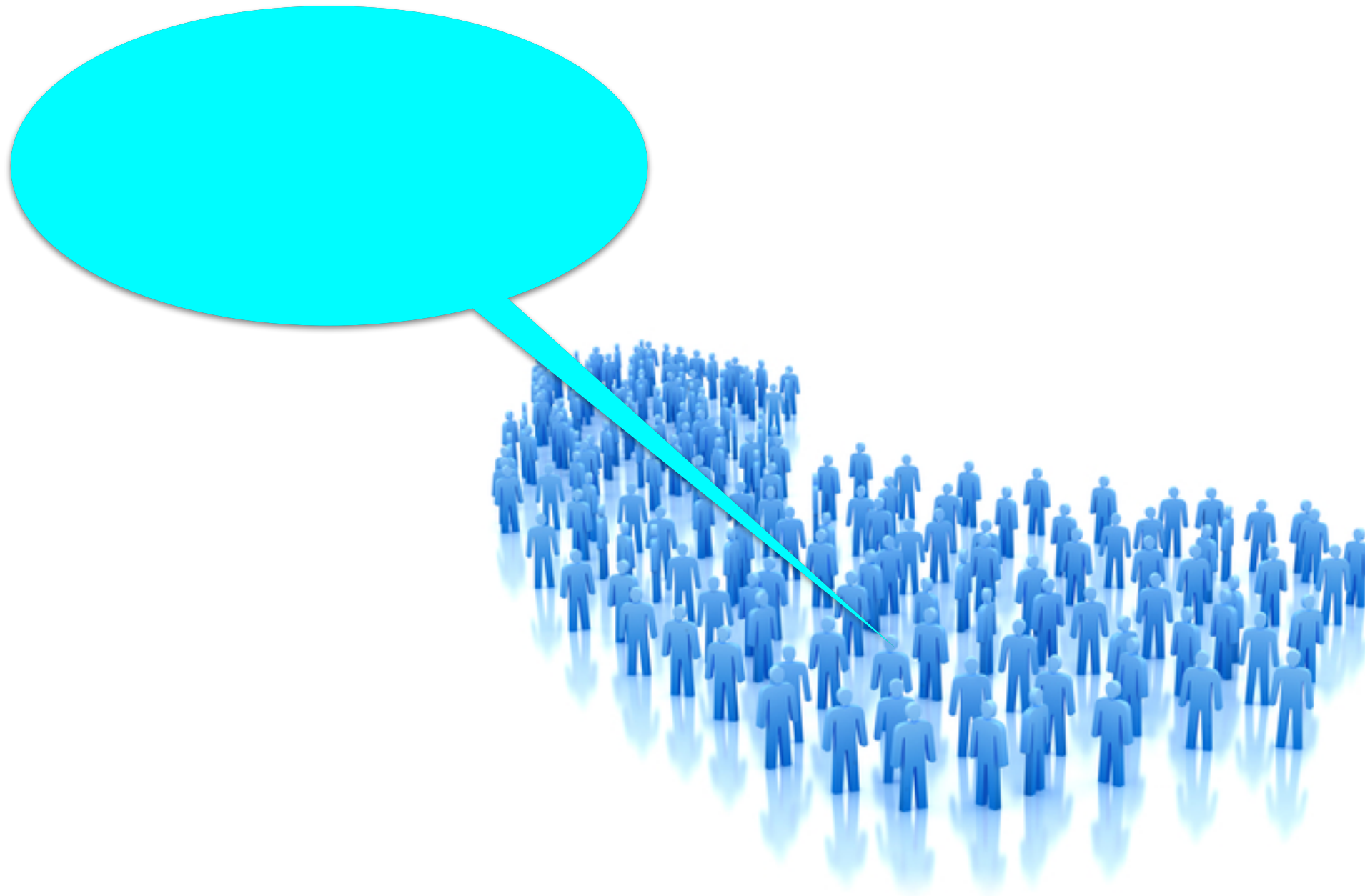
How do you count the size of your group,  
if the members are all identical and move?





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How do you count the size of your group,  
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# The Counting Problem

How do you count the size of your group,  
if the members are all identical and move?

You all look the same,  
did I already count you?



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# The Counting Problem

How do you count the size of your group,  
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You all look the same,  
did I already count you?

I don't know!  
You also look the same as  
everyone else!!



# Why do we care?

The problem is clean, but why do we care?

Distributed algorithms

need the number of processors to decide **termination**.

We need a **protocol**: « Given a system of  $n$  nodes,  
all nodes eventually terminate knowing  $n$  »



# Previous work

- **Previous Counting Protocols**

- Guarantee only an exponential upper bound on the network size [1] or
- They guarantee the exact size but
  - Take **double-exponential** number of rounds [2] or
  - Take exponential number of rounds, but **do not terminate** [2] or
  - Terminate but **no running-time guarantees** [3].
- Recently, exact-size exponential time Counting with termination:
  - [5] Incremental Counting (IC): needs dyn. max degree  $d_{\max}$ , poly space.
  - [6] EXT Counting: no  $d_{\max}$ , but exponential space.

Exponential speedup,  
but still not practical

- **Lower bound on the time complexity**

- $\Omega(D)$  where  $D$  is the dyn. diameter.
- $\Omega(\log n)$  even if  $D$  is constant [4].

Huge gap

- **Experimental work**

- IC on trees, paths, stars,  $G(n,p)$  [7].

Polynomial in practice

[1] O. Michail, I. Chatzigiannakis, and P. G. Spirakis. Naming and counting in anonymous unknown dynamic networks. SSS 2013.

[2] G. A. Di Luna, R. Baldoni, S. Bonomi, and I. Chatzigiannakis. Conscious and unconscious counting on anonymous dynamic networks. ICDCN 2014.

[3] G. A. Di Luna, R. Baldoni, S. Bonomi, and I. Chatzigiannakis. Counting in anonymous dynamic networks under worst-case adversary. ICDCS 2014.

[4] G. A. Di Luna and R. Baldoni. Investigating the cost of anonymity on dynamic networks. 2015.

[5] A. Milani and M. A. Mosteiro. A faster counting protocol for anonymous dynamic networks. OPODIS 2015.

[6] R. Baldoni and G. A. Di Luna. Non trivial computations in anonymous dynamic networks. OPODIS 2015.

[7] M. Chakraborty, A. Milani and M. A. Mosteiro. Counting in practical anonymous dynamic networks is polynomial. NETYS 2016.

# Previous work

restrictions/  
shortcomings

algorithm	needs		computes	stops?	complexity	
	size upper bound $N$	dynamic maximum degree u.b. $d_{\max}$			time	space
<i>Degree Counting</i> [20]		✓	$O(d_{\max}^n)$	✓	$O(n)$	
<i>Conscious</i> [10]	✓	✓	$n$	✓	$O(e^{N^2} N^3) \Rightarrow$ $O(e^{d_{\max}^{2n}} d_{\max}^{3n})$ using [20]	
<i>Unconscious</i> [10]			$n$	No	No theoretical bounds	
$\mathcal{A}_{OP}$ [11]		Oracle for each node	$n$	Eventually	Unknown	
EXT [9]			$n$	✓	$O(n^{n+4})$	EXPSPACE
INCREMENTAL COUNTING [21]		✓	$n$	✓	$O\left(n (2d_{\max})^{n+1} \frac{\ln n}{\ln d_{\max}}\right)$	
METHODICAL COUNTING [This work]			$n$	✓	$O(n^5 \ln^2 n)$	PSPACE

[20] O. Michail, I. Chatzigiannakis, and P. G. Spirakis. Naming and counting in anonymous unknown dynamic networks. SSS 2013.

[10] G. A. Di Luna, R. Baldoni, S. Bonomi, and I. Chatzigiannakis. Conscious and unconscious counting on anonymous dynamic networks. ICDCN 2014.

[11] G. A. Di Luna, R. Baldoni, S. Bonomi, and I. Chatzigiannakis. Counting in anonymous dynamic networks under worst-case adversary. ICDCS 2014.

[21] A. Milani and M. A. Mosteiro. A faster counting protocol for anonymous dynamic networks. OPODIS 2015.

[9] R. Baldoni and G. A. Di Luna. Non trivial computations in anonymous dynamic networks. OPODIS 2015.

# Contributions

- Methodical Counting (MC) algorithm:
  - no knowledge of network characteristics
  - computes the exact size of the network
  - all nodes obtain  $n$  and terminate
  - **first polynomial time** guarantees
  - **exponentially faster** than best previous work
- Design of control mechanisms:
  - for mass-distribution-based computations,  
to detect wrong convergence-time estimation
- Novel approach opens path:
  - to study more complex computations using same techniques
- Extensions to algebraic and other computations:
  - sum, average, max, min, multiple Boolean functions, others



# MC Key Ingredients

Key idea:

- distribute a potential value iteratively (resembling previous works),
- but let the leader participate in the process as any other node,
- **leader removes potential but only after it has accumulated enough!**

# MC Key Ingredients

Our approach allows to leverage previous work on  
lazy random walks in evolving graphs [1].

But, **not a simple de-randomization,**

- In ADNs, neighbors cannot be distinguished.  
so, we use lazy random walks bounds,
- Even number of neighbors unknown at transmission time,  
but only when parameters are temporarily fixed,  
only after receiving but may change for next round.
- Unknown network parameters  $\Rightarrow$  and the number of received messages is not invalid.  
potential received could be bigger than 1.
- Mixing and cover time of lazy random walks depend on  $n \Rightarrow$   
**cannot be used for termination.**

# MC Structure

epochs:

- one for each estimate  $k=2,3,\dots,n$
- initially, “potential” value:  $\Phi_{\text{non-leader}}=1$ ,  $\Phi_{\text{leader}}=0$

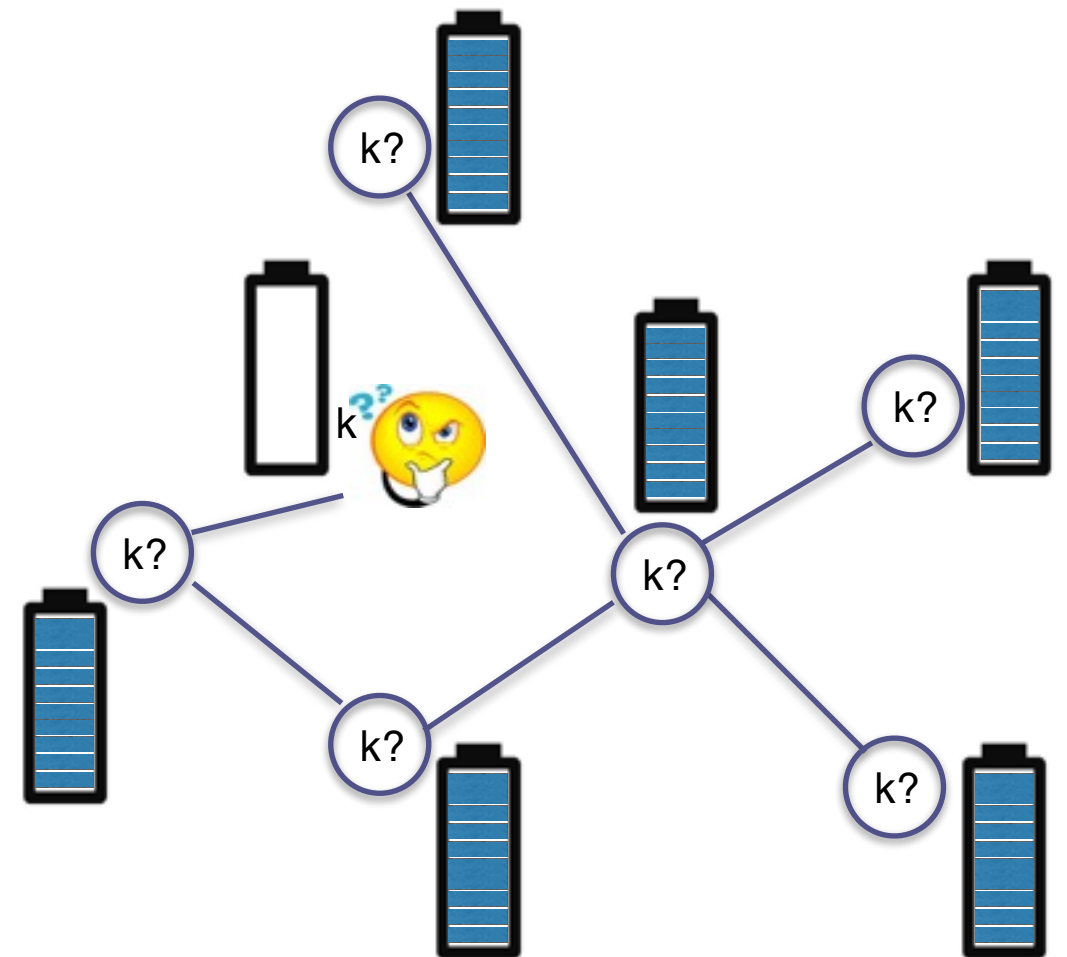
$p(k)$  phases:

(to let the leader remove “enough” potential  $\rho$ )

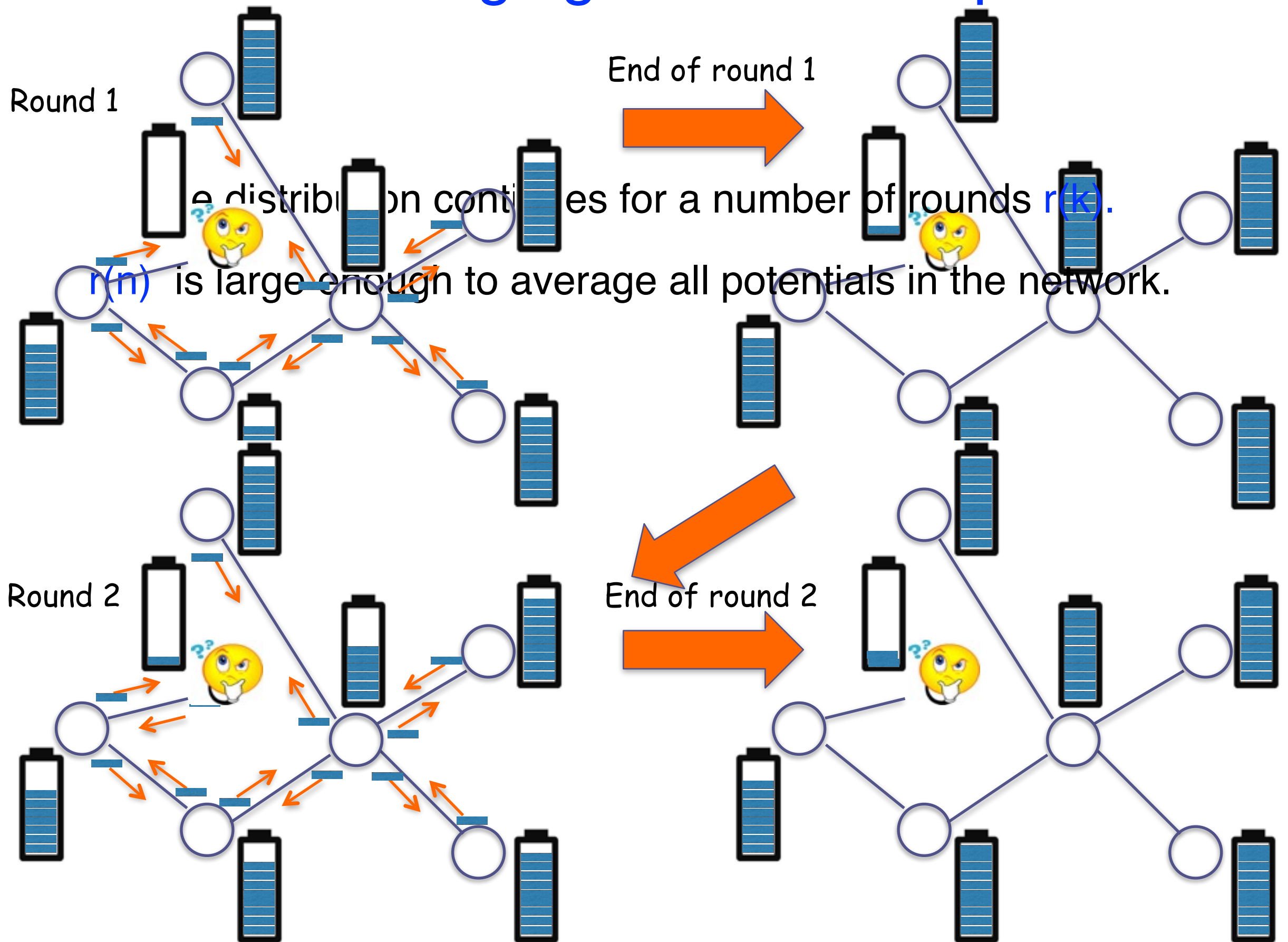
$r(k)$  rounds:

(to “average” the current potentials  $\Phi$ )

let's see how...



# MC Averaging Phase Example



# MC Epoch Example

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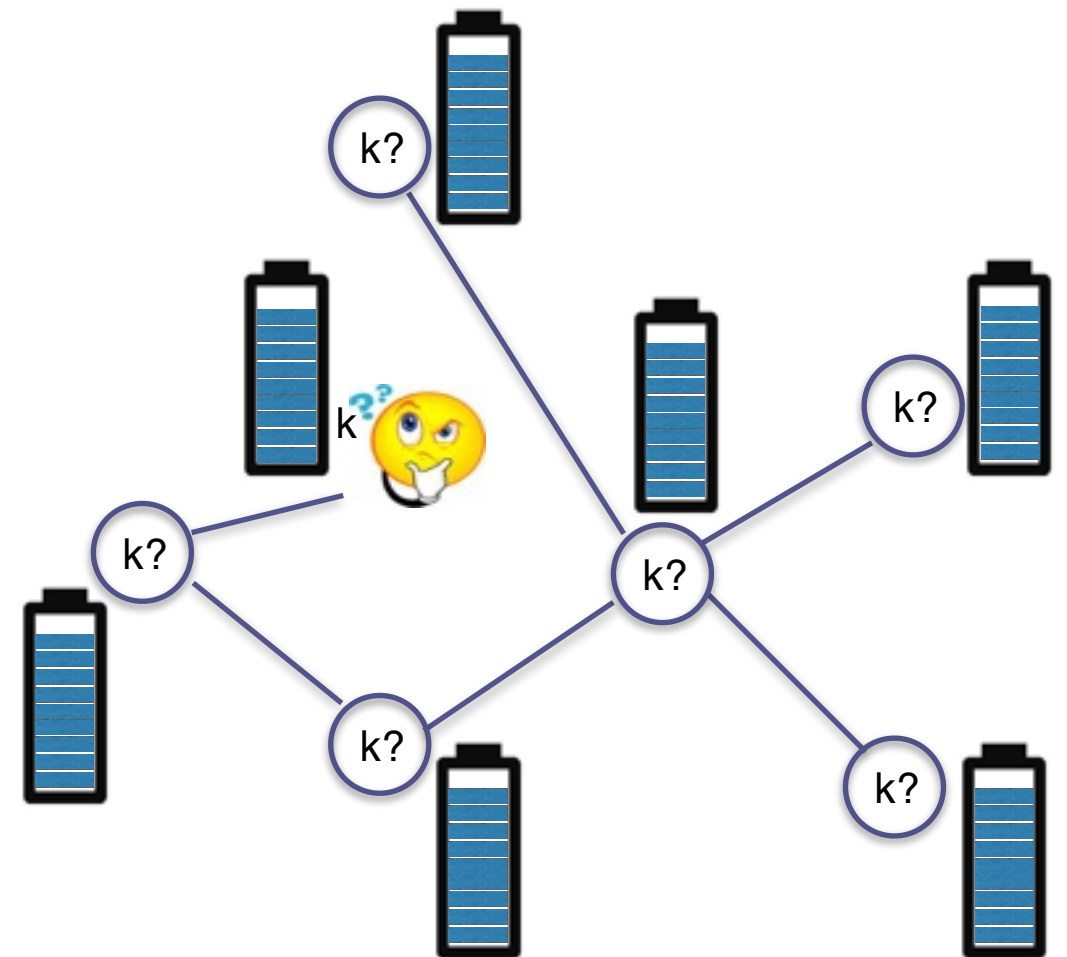
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mass distribution:

- broadcast  $\Phi$  and receive neighbors'  $\Phi_i$
  - $\Phi = \Phi + \sum_{i \in N} \Phi_i / d(k) - |N| \Phi / d(k)$
- leader “removes” its potential:  $\rho = \rho + \Phi$ ,  $\Phi = 0$



$\rho =$



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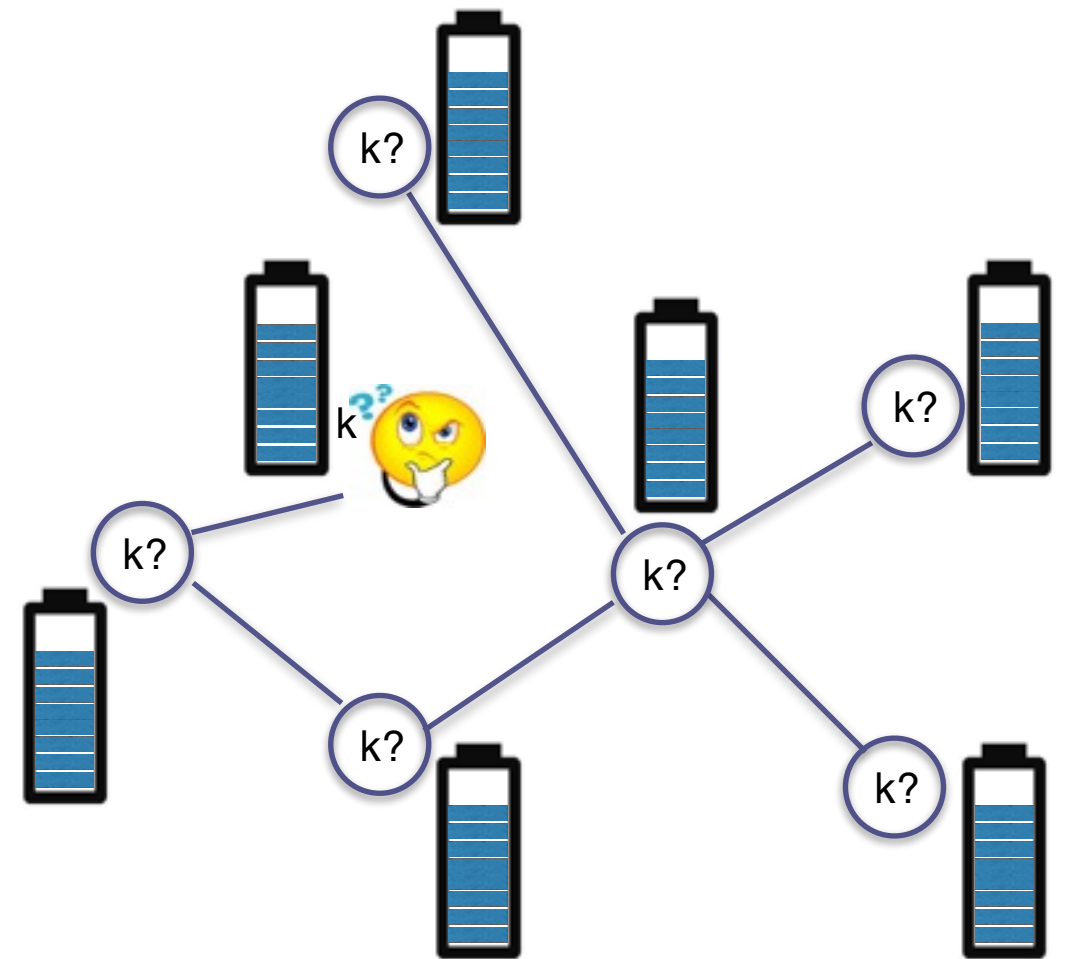
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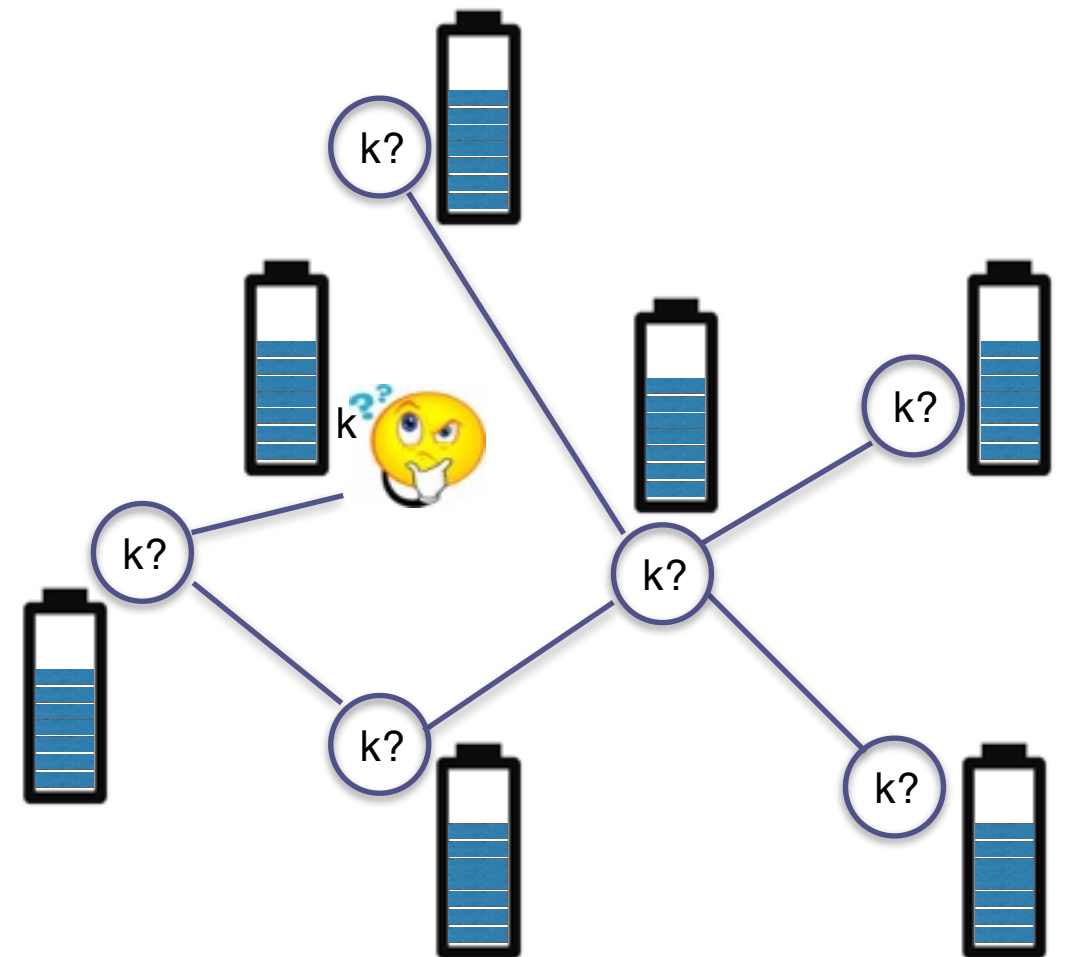
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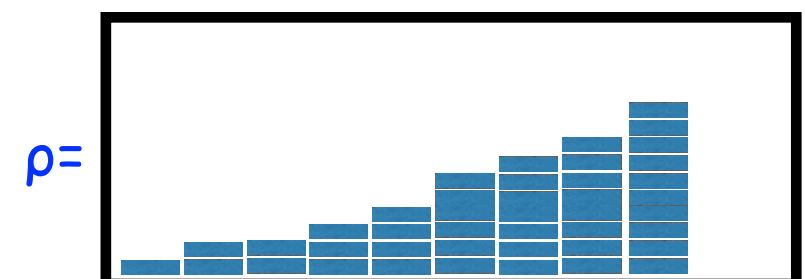
- if  $\rho < k-1-1/k$  or  $\rho > k-1$ 
  - try next  $k$
- else notify all nodes that  $k=n$

After  $p(k)$  phases...

Analysis shows that if  $\rho < k-1-1/k$  or  $\rho > k-1$  then  $k < n$ .

Else ( $k-1-1/k \leq \rho \leq k-1$ ) we would like to say  $k=n$ , but not always true!

We use some previous alarms to detect  $k < n$  in those cases...



# MC Alarms (for $k < n$ )



If  $n$  is “close” to  $k$  then  
leader removes  
“too much” potential.

If  $n$  is “far” from  $k$  then  
not “many” nodes  
have “low” potential,

so, leader receives alarm from  
nodes with “high” potential  
“soon” after first phase.

# MC Epoch Example

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- leader “removes” its potential:  $\rho = \rho + \Phi$ ,  $\Phi = 0$
- if  $k-1-1/k \leq \rho \leq k-1$  and status = normal
  - notify all nodes that  $k=n$
- else try next  $k$

We use some previous alarms to detect  $k < n$  in those cases.

And now the leader can notify  $k=n$  when  $\rho$  is in that range.



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# Main Theorem

**THEOREM 6.2.** *Given an Anonymous Dynamic Network with  $n$  nodes, after running METHODICAL COUNTING for each estimate  $k = 2, 3, \dots, n$  with parameters*

$$\begin{aligned}d &= k^{1+\epsilon}, \\p &= \left\lceil \frac{(2 + \epsilon)k^{1+\epsilon}}{1 - 1/k} \ln k \right\rceil, \\r &= \left\lceil \left( 4 + 2\epsilon + \max \left\{ 0, -\frac{2 \ln(k^\epsilon - 1)}{\ln k} \right\} \right) dk^{2+2\epsilon} \ln k \right\rceil, \\\tau &= 1 - 1/k^{1+\epsilon},\end{aligned}$$

*where  $\epsilon > 0$ , all nodes stop after  $\sum_{k=2}^n (pr + k)$  rounds of communication and output  $n$ .*

**COROLLARY 6.1.** *The time complexity of METHODICAL COUNTING is  $O(n^5 \log^2 n)$ .*

# MC Extensions

SUM: assume each node  $i$  stores a value  $v_i$ ,  
and we need to compute the exact sum.

Compute  $n$  and SUM simultaneously:

For each node  $i$

- Append to potential  $\phi_i$  the bit representation of value  $v_i$  as a sequence of values (initially in  $\{0,1\}$  but later averaged iteratively and independently).

$$\langle \phi_i, v_{i0}, v_{i1}, v_{i2}, \dots \rangle$$

- Apply same algorithm to each  $v_{ij}$  independently, as well as to the potential.
- Store the  $v_{ij}$ 's at the end of each first phase, call them  $v'_{ij}$ .
- At the end of each epoch while  $k < n$ , reset to the original  $v_{ij}$ 's.
- At the end of last epoch ( $k=n$ ), compute  $\sum_j \lceil n v'_{ij} \rceil 2^j$ .

Others: AVG, Boolean (AND, OR, XOR, etc.), some database queries.

# Future and Ongoing Work

- Many leaders.
- Improve upper and lower bounds.
- Other computations in ADNs.
- Asynchronous protocol.

Thank you!

