

# Initializing Sensor Networks of Non-uniform Density in the Weak Sensor Model

Martín Farach-Colton<sup>1</sup>   Miguel A. Mosteiro<sup>2</sup>

<sup>1</sup>Department of Computer Science  
Rutgers University

<sup>2</sup>LADyR (Distributed Algorithms and Networks Lab)  
Universidad Rey Juan Carlos

WADS 2007

# A Sensor Network



*Intel Berkeley Research Lab*

## Capabilities

- processing
- sensing
- communication

## Limitations

- range
- memory
- life cycle



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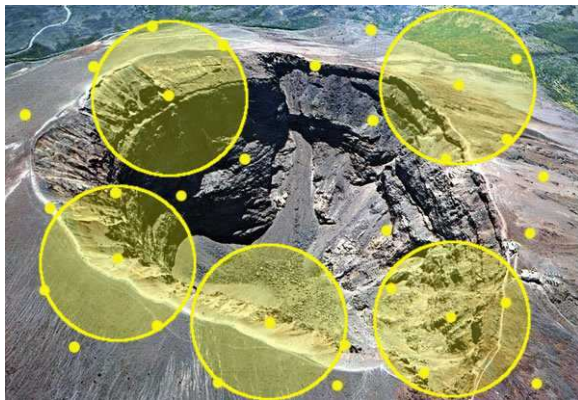
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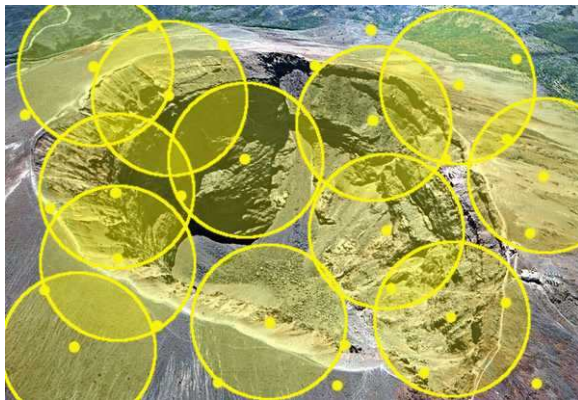
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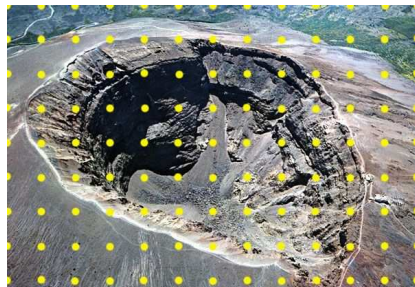
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# Node Layout



Radio Networks: arbitrary



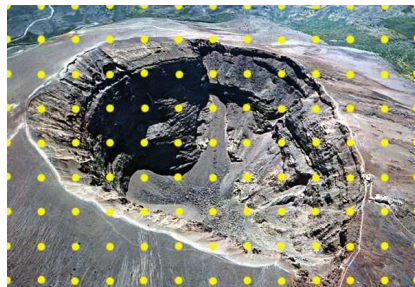
Sensor Networks: uniform

Example of a feasible model:  
a multiple bivariate normal distribution.

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More generally, we assume a **Smooth Distribution**:

- 1 In any disc of radius  $r/2$ :  
the number of nodes is at most some  $\Delta \leq n$ .
- 2 For any const.  $\alpha > 0$ , in any disc of radius  $\alpha r$ ,  $\exists$  const.  $\beta > 0$  such that:  
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# Sensor Network Bootstrapping

Communication is through radio broadcast.

Still, explicit links are necessary.

Lack of collision detection and unknown topology  $\Rightarrow$   
establishing them from scratch is not trivial!

- How do we understand limitations?

The Weak Sensor Model.

- How are sensors distributed?

Geometric Graph.

- What kind of network do we want?

Hop-optimal,  $O(1)$  degree (concludes from WSM).[FCFM05]

- Under smooth distributions:

Still any connected GG has a hop-optimal subgraph,  $O(1)$  degree.

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# Previous Work

## Upper Bounds

### Sensor Network formation:

- Sohrabi et al., 00: Flat topology.  
Number of channels function of density.
- Blough et al., 03: k-neighbors protocol.  
Distance estimation.
- Song et al., 04: OrdYaoGG structure power spanner.  
Distance estimation, directional antenna.

All: memory size function of density and no contention resolution in the analysis.

- FCFM, 05:  $O(\log^2 n)$ , whp, Sensor Network bootstrapping (RGG).

# Previous Work

## Lower Bounds

Clear Transmissions:

- KM-98:  $\Omega(\log n)$ , expected.
- JS-02:  $\Omega\left(\frac{\log n \log(1/\epsilon)}{\log \log n + \log \log(1/\epsilon)}\right)$ , wp  $1 - \epsilon$ , uniform, one-hop.
- FCFM-06:  $\Omega(\log n \log(1/\epsilon))$  wp  $1 - \epsilon$ , uniform, one-hop.  
 $\Omega(\log \log n \log(1/\epsilon))$  wp  $1 - \epsilon$ , uniform, RGG.

# Our Results

## Lower Bounds

- Clear transmission:
  - a node produces a clear transmission at time  $t$ ,
  - if every two-hop neighbor does not transmit in  $t$ .
- Clear Transmission problem:
  - every node has to either receive or produce a clear transmission.
- Group Therapy problem:
  - every node must be *heard*.
- Regardless of randomization:
  - $\Omega(\Delta)$  for group therapy.
- Uniform protocols:
  - $\Omega(\Delta + \log \Delta \log(1/\epsilon))$ , w.p.  $1 - \epsilon$ , using previous clear transmission bound.
- Fair protocols:
  - $\Omega(\Delta(\log \Delta + \log(1/\epsilon)))$ , w.p.  $1 - \epsilon$ , for group therapy.
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## Upper Bounds

- Under smooth distributions and the WSM:
  - distributed protocol builds  $O(1)$ -degree hop-optimal network,  
each node joins the network w.h.p. within  $O(\Delta \log n)$  steps.
- Includes  $O(\Delta \log n)$ -fair protocol where
  - each* node produces a Clear Transmission.
  - If every node produces a Clear Transmission
    - $\Rightarrow$  Group Therapy problem is solved
    - $\Rightarrow$  this protocol matches the lower bound.



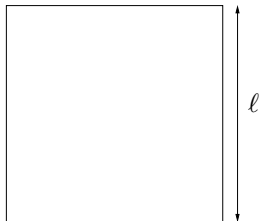
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- 1 Introduction
- 2 Model
- 3 Lower Bounds
- 4 Upper Bounds

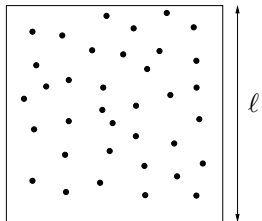
# Connectivity



The geometric graph model  $\mathcal{G}_{n,r,\ell}$ .

- $[0, \ell]^2$
- Structural properties depend on relation among  $r$ ,  $n$  and  $\ell$ .

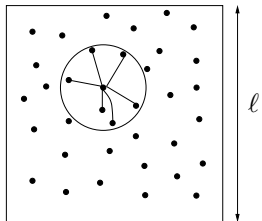
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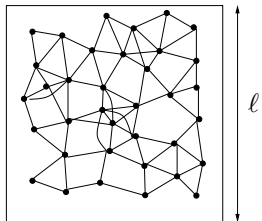
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# Node Constraints

## THE WEAK SENSOR MODEL[FCFM05]

- CONSTANT MEMORY SIZE.
- LIMITED LIFE CYCLE.
- SHORT TRANSMISSION RANGE.
- LOW-INFO CHANNEL CONTENTION:
  - RADIO TX ON A SHARED CHANNEL.
  - NO COLLISION DETECTION.
  - NON-SIMULTANEOUS RX AND TX.
- DISCRETE TX POWER RANGE.
- LOCAL SYNCHRONISM.
- ONE CHANNEL OF COMMUNICATION.
- NO POSITION INFORMATION.
- UNRELIABILITY.
- ADVERSARIAL WAKE-UP SCHEDULE.

$tx = \text{transmission.}$   
 $rx = \text{reception.}$

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# A reduced model for a stronger lower bound

- Shared channel.
- No collision detection.
- Non simultaneous transmission and reception.
- Local synchronization.
- Adversarial wake up.

Known in the literature as: Radio Network.

# Definitions

**Fair protocol:** sequence  $p_1, p_2, \dots$

- every active node transmits with probability  $p_\ell$  at time-slot  $t_\ell$ .
- $p_\ell \in \{2^{-j} | 1 \leq j \leq \log n\}$ .

**Adversary:**

- Wakes up  $2^i$  *active* nodes at time  $t_1$  in a neighborhood of density  $\Delta$ ,  $i \in [1, \log \Delta]$ .
- Active nodes: stay active and run the protocol.
- Non-active nodes: do not participate in the protocol.

# LP formulation

Let

- $p_{ij} \triangleq$  probability that a node fails to achieve a non-colliding transmission when  $2^i$  active nodes transmit with probability  $2^{-j}$ .
- $t_j \triangleq$  number of time slots where nodes transmit with probability  $2^{-j}$ .

Then, for each  $i \in [1, \log \Delta]$ , we want

$$2^i \prod_j p_{ij}^{t_j} \leq \epsilon$$

$$\sum_j t_j \ln(p_{ij}) \leq \ln(\epsilon) - \ln 2^i.$$

We can obtain a lower bound minimizing the total number of time slots under these constraints  $\rightarrow$  LP?

# LP formulation

$$\sum_j t_j \ln(p_{ij}) \leq \ln(\epsilon) - \ln 2^i$$

primal

Minimize  $\mathbf{1}^T \mathbf{t}$ ,  
subject to:

$$\begin{aligned} \mathbf{P} \mathbf{t} &\geq \boldsymbol{\epsilon} \\ \mathbf{t} &\geq \mathbf{0} \end{aligned}$$

dual

Maximize  $\boldsymbol{\epsilon}^T \mathbf{u}$ ,  
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Where:

$$\mathbf{t} \triangleq [t_j]$$

$$\boldsymbol{\epsilon} \triangleq [-\ln(\epsilon) + \ln 2^i]$$

$$\mathbf{P} \triangleq [-\ln(p_{ij})]$$

Primal LP has a finite solution  $\Rightarrow$  dual LP has a finite solution  
 $\Rightarrow$  any feasible objective function value for the dual  
 is a lower bound on the value of the primal!  
 (Weak LP Duality Theorem)

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Slack variables  $u_i = 2^i \left(1 - \frac{1}{\sqrt{e}}\right)^2$  verify these constraints, then...

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Theorem

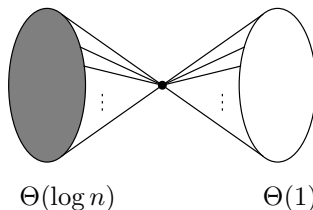
$$\mathbf{1}^T \mathbf{t} \in \Omega(\Delta(\log \Delta + \log(1/\epsilon)))$$

# Clear Transmissions

Fair protocols under uniform distributions

## Adversary:

- Wakes up  $\Theta(n/\log n)$  disjoint *clique-pairs* at time  $t_1$ .
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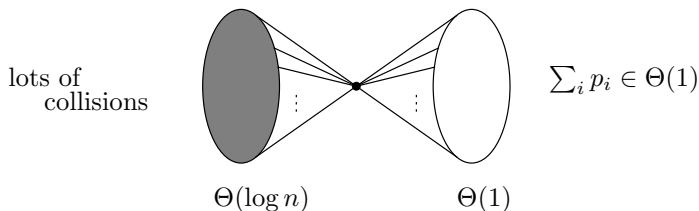


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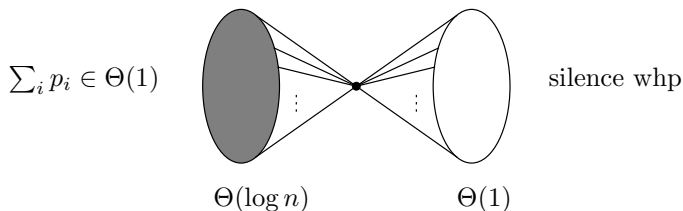


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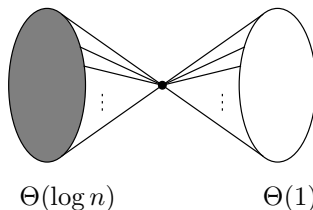


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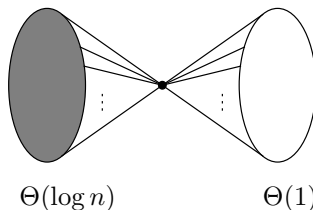
Minimizing the probability of failing to achieve a Clear Transmission in a low density clique...

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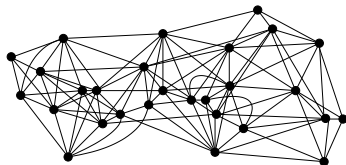
## Theorem

$\Omega(\log^2 n)$  expected time to solve the Clear Transmission problem.

# Disk-cover Algorithm

[FCFM-05]

Given an RGG, find a CHSG as follows:

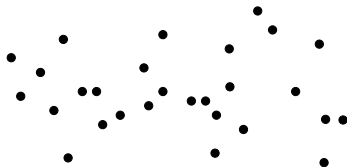


- Add all nodes.
- Lay down disks of radius  $ar/2$ ,  $0 < a < 1$  centered on uncovered nodes.
- Add all edges that connect these *bridges*.
- Expand the disks to a radius of  $br/2$ ,  $a < b < 1$ .
- Add edges to form a constant-degree *disk-spanner*.

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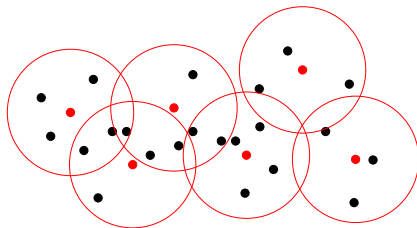


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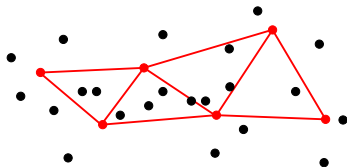


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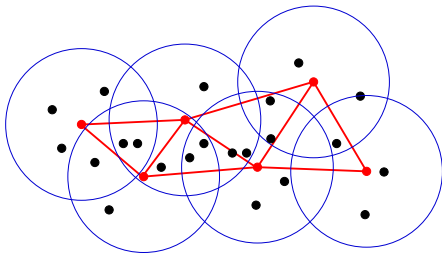
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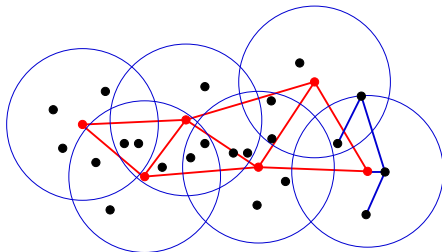


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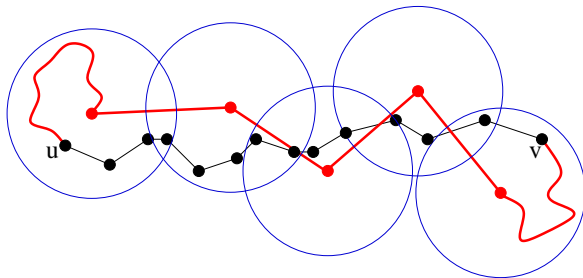
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# Hop-optimality

What is the optimal path between  $u$  and  $v$ ?



Theorem (FCFM-05)

$d(u, v) \in O(D(u, v)/r + \log n)$  is asymptotically optimal.

We need a logarithmic diameter...

# Spanner Construction

- ❶ **Predecessor-identification phase:** every node broadcasts its ID for  $\gamma_1 \Delta \log n$  steps with probability  $1/\Delta$ ,  $\gamma_1 > 0$  some constant.
- ❷ **Self-enumeration phase:** upon receiving the rank  $i$  of its predecessor, a node defines its rank as  $i + 1$  and broadcasts it with constant probability  $p < 1$  for  $\gamma_2 \log n$  steps,  $\gamma_2 > 0$  some constant.
- ❸ **Link-definition phase:** Each node broadcasts its ID and rank for  $\gamma_1 \Delta \log n$  steps with probability  $1/\Delta$ .

## Lemma

*If every node repeatedly transmits with probability  $1/\Delta$  every node achieves a Clear Transmission within  $O(\Delta \log n)$  time steps w.h.p.*

## Theorem

*Any node running the spanner algorithm joins the spanner within  $O(\Delta \log n)$  time steps w.h.p.*

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Thank you